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Assessing the Sprinkler Activation Predictive Capability of the BRANZFIRE Fire Model

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ABSTRACT

This paper describes an investigation into the sprinkler response time predictive capability of the BRANZFIRE fire model. A set of 22 fire/sprinkler experiments are simulated where the sprinkler activation time and the heat release rate (HRR) for each individual experiment had been determined. The experiments provided data for use in validating the sprinkler activation prediction algorithms in the BRANZFIRE zone model.

A set of base case values were chosen and input files constructed for the simulations. The experiments were then simulated by the fire model using both the NIST/JET ceiling jet and Alpert's ceiling jet options (which are the two ceiling jet correlations available in the BRANZFIRE zone model). The fire model included a heat transfer calculation for the temperature of the heat sensitive sprinkler element. Different sprinkler operational parameters such as the conduction factor, response time index (RTI) and the sprinkler depth below ceiling were also varied to assess the sensitivity of their effect on the activation time.

Results showed that using the NIST/JET ceiling jet algorithm gave a closer prediction of the sprinkler response time in a small room than Alpert's correlation. This was expected, since the former includes the effect of a hot upper layer while the latter applies to unconfined ceilings. The experiments available for comparison had been conducted inside an enclosure with a developing hot upper layer. The findings also signified that changing the sprinkler operational parameters can change the predicted sprinkler activation time significantly.

Key words: fire modelling, verification and validation, sprinkler response, BRANZFIRE.

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INTRODUCTION

General

In recent years, as a result of a greater interest in performance-based design, increased building design complexity and advances in computer processing power, the development and use of computer tools for simulating fire have grown dramatically. Computer fire models play an important role in many fire engineered solutions by assisting engineers to better understand likely fire behaviour and its effects in a given building.

Computer models vary considerably in complexity from simple zone models to sophisticated computational fluid dynamic models. They also include many special-purpose codes for predicting specific phenomena such as glass breakage or heat detector activation. However, all models require validation before they can be used with confidence.

A heat detector response model is intended to predict the time at which a heat detector is expected to operate given the properties of the detector and the fire environment to which it is exposed. This paper describes research on the validation of a heat sensor model that has been incorporated within an existing fire zone model [1]. In this case, the heat sensor is a glass bulb sprinkler head.

There have been a number of models previously developed to predict the response time of sprinklers. The better known models include DETACT-QS [2], LAVENT [3] and JET [4]. Parts of these models have been drawn upon in implementing the sprinkler response model described in this paper.

Background

During the growth stage of a fire, the smoke environment in a room can be represented by two layers, a hot upper layer and a cool lower layer (as shown in Figure 1). In the early stages of fire development, the temperature of the lower layer is close to ambient. The temperature of the upper layer, however, rises as the plume above the fire transports smoke and hot gases into the upper layer along with a significant volume of entrained air. Once the plume reaches the ceiling, hot gases travel beneath the ceiling in a radial direction away from the plume. This hot gas flow is known as the ceiling jet, the properties of which strongly influence the operation of fire detectors and sprinklers.

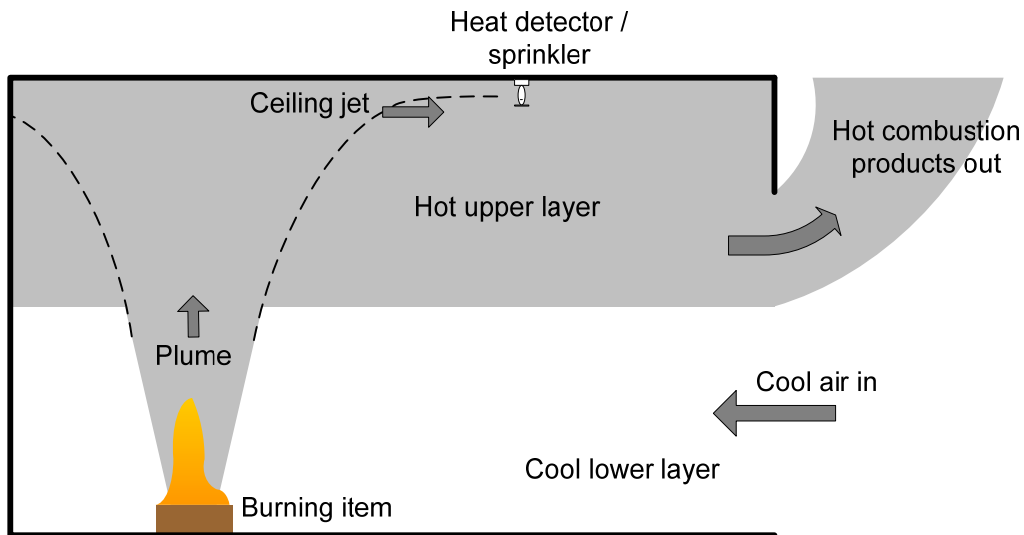


Figure 1. Room fire development

The activation time of the sprinkler is the time at which the temperature of the sprinkler bulb reaches the nominal activation temperature. Convective heat transfer from the flowing gases in the ceiling jet to the sprinkler bulb is the primary heat transfer mechanism. However, for an enclosure where the ceiling jet is immersed in a hot layer, additional heat transfer from the hot layer to the sprinkler occurs. There are also heat conduction losses from the sprinkler head to the attached pipework.

The best known ceiling jet model is that developed by Alpert [5] who described the gas temperature and velocity in a ceiling jet dependent on the fire size, ceiling height and radial distance from the centre of the fire plume. This was based on fire gases flowing beneath an unconfined ceiling. More recently, Davis [6] developed a detailed mathematical description of the ceiling jet taking into account the presence of a hot upper layer.

Both these ceiling jet models were incorporated into an existing fire zone model [1] allowing fire development in an enclosure to be simulated along with predictions of sprinkler response time.

MODEL DESCRIPTION

Zone model

BRANZFIRE [1] is a zone model used to calculate the time-dependent distribution of smoke, fire gases and heat throughout a collection of connected compartments during a fire. Each compartment is divided into two layers – a hot upper layer and a cool lower layer. The conservation equations used take the mathematical form of an initial value problem for a system of ordinary differential equations (ODE). These equations are derived using the laws of conservation of mass and energy, the ideal gas

law and related equations for density and enthalpy, and are in a form given by Peacock et al [7]. These equations predict time varying quantities such as pressure, layer heights and temperatures given the accumulation of mass and enthalpy in each layer. The model solves the set of ODE's to determine the environment in each compartment layer. The equation for the rate of the change of the pressure in the room, P , is (variables are defined in the nomenclature):

$$\frac{dP}{dt} = \frac{\gamma - 1}{V_R} (\dot{h}_l + \dot{h}_u)$$

This is the gauge pressure at floor level in the compartment, relative to atmospheric pressure at a nominated reference elevation. The equations for the rate of change of the upper layer volume, V_u , and upper and lower layer temperatures, T_u and T_l respectively, are:

$$\begin{aligned} \frac{dV_u}{dt} &= \frac{1}{\gamma P} \left[(\gamma - 1) \dot{h}_u - V_u \frac{dP}{dt} \right] \\ \frac{dT_u}{dt} &= \frac{1}{c_p \rho_u V_u} \left[(\dot{h}_u - c_p \dot{m}_u T_u) + V_u \frac{dP}{dt} \right] \\ \frac{dT_l}{dt} &= \frac{1}{c_p \rho_l V_l} \left[(\dot{h}_l - c_p \dot{m}_l T_l) + V_l \frac{dP}{dt} \right] \end{aligned}$$

Heat transfer to the sprinkler element

The differential equation describing the rate of change of temperature of the sensing element of the sprinkler, T_e , with time is from Heskestad and Bill [8]. Both convective heating of the sensing element and conductive losses to the sprinkler piping are incorporated. The equation used is:

$$\frac{dT_e}{dt} = \frac{\sqrt{U_{cj}} (T_{cj} - T_e)}{RTI} - \frac{C(T_e - T_{int})}{RTI}$$

The predicted sprinkler response time is based on a single burning object located within the room of fire origin. There are two algorithms available for predicting sprinkler response in BRANZFIRE. One uses Alpert's [5] unconfined ceiling jet correlation, while the other uses the JET algorithm developed at National Institute of Standards and Technology [6].

Alpert's correlations

The empirical correlations developed by Alpert [5] for the temperature, T_{cj} , and velocity, U_{cj} , of the ceiling jet are:

$$T_{cj} - T_{int} = \begin{cases} \frac{16.9\dot{Q}^{2/3}}{H^{5/3}} & \text{for } \frac{r}{H} \leq 0.18 \\ \frac{5.38(\dot{Q}/r)^{2/3}}{H} & \text{for } \frac{r}{H} > 0.18 \end{cases}$$

$$U_{cj} = \begin{cases} 0.96\left(\frac{\dot{Q}}{H}\right)^{1/3} & \text{for } \frac{r}{H} \leq 0.15 \\ \frac{0.195\dot{Q}^{1/3}H^{1/2}}{r^{6/5}} & \text{for } \frac{r}{H} > 0.15 \end{cases}$$

These correlations are for the maximum temperature and velocity in an unconfined ceiling jet. Variation of temperature and velocity with distance beneath the ceiling is ignored, so it is implicitly assumed that the sprinkler link is located at the distance below the ceiling at which these maximum values occur.

JET algorithm

The JET algorithm developed at NIST by Davis et al [6], along with the subsequent zone model [4] of the same name, predicts the plume centreline temperature, the ceiling jet temperature and the ceiling jet velocity produced by a single fire plume. The unique feature of this algorithm is that the characteristics of the ceiling jet depend on the temperature and depth of the hot layer. The characteristics of the hot layer are calculated from the mass and energy balance equations solved by the fire model (BRANZFIRE). The detailed equations that describe the JET algorithm are published elsewhere [4, 6].

An enhancement to the JET model [6] was made by including the variation of ceiling jet temperature and velocity with depth, from the ceiling surface to the depth at which the maximum temperature occurs [9]. Below that distance it is then assumed that the maximum ceiling jet temperature reduces asymptotically to equal the hot layer temperature at the level of the smoke layer interface. The variation of the ceiling jet temperature and velocity with distance below the ceiling is incorporated using the LAVENT method described in NFPA 204 Appendix B [9]. At the ceiling, the ceiling jet temperature equals the ceiling surface temperature and then increases to a maximum value at a depth, d_{max} , below the ceiling given by:

$$d_{max} = 0.023H(r/H)^{0.9}$$

This equation only applies outside the fire plume region where $r/H > 0.2$. At greater depths beneath the ceiling, the temperature reduces asymptotically to equal the hot layer temperature at the level of the smoke layer interface. An example is illustrated later.

Assumptions that apply with both the Alpert and JET models include:

- compartment pressure near ambient
- flames do not touch the ceiling
- fire is located in centre of compartment
- fire is fully ventilated
- ignores transport time
- ignores radiant heating of link/bulb.

For fires located adjacent to a corner or wall, the HRR used in the ceiling jet correlation is modified assuming the method of reflection (i.e. uses $2\dot{Q}$ or $4\dot{Q}$ for wall and corner fires respectively).

EXPERIMENTS

Experiment description

A set of 22 fire experiments where a single chair was burned in an enclosure were conducted. Two sprinkler heads were installed for each experiment and the sprinkler activation time, chair mass loss rate and gas temperature profile in the room were measured and reported by Bittern [10]. The HRR was estimated by Bittern from the measured mass loss rate and the effective heat of combustion of the fuel [10]. A bare-wire Type K thermocouple was located adjacent to each sprinkler head, and stainless steel sheathed, mineral insulated Type K thermocouples were used to measure the gas temperature, away from the sprinkler, at depths of 0.1 m, 0.3 m and 1.4 m below the ceiling.

Two different fire location positions (centre and corner of the enclosure) and two different door configurations (open and shut) were investigated. Table 1 summarises the position of the fire and the door configuration for each experiment. Experiment 11 was excluded for this comparison as no mass loss data for the chair was collected.

The compartment was built from timber-framed walls and ceiling and lined with painted 10 mm thickness gypsum plasterboard. The compartment had internal dimensions of 8 m x 4 m x 2.4 m high and was based on the room specifications contained in UL 1626 [11]. The compartment layout is

shown in Figure 2. The door set was made of a wooden frame with a plywood door leaf with dimensions of 0.8 m wide x 2.1 m high. The floor of the compartment was concrete.

Table 1. Fire position and door configuration

Experiment no.	Fire position	Door configuration
1–10	Centre	Open
12–15	Centre	Shut
16–22	Corner	Shut

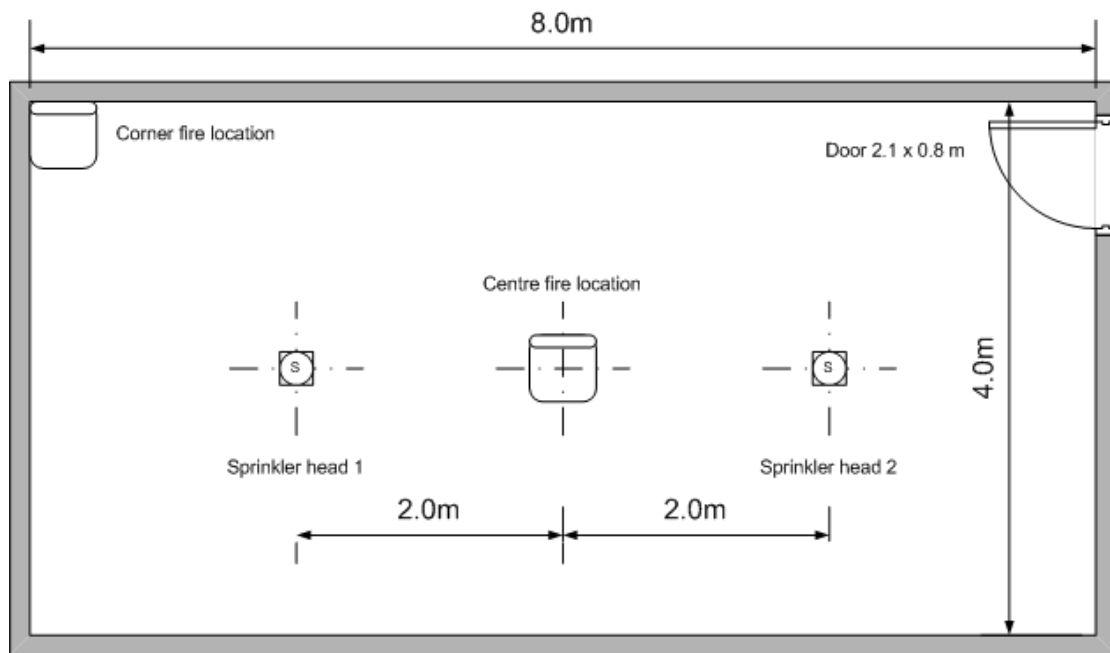


Figure 2. Compartment layout (plan view)

The fuel package used for each experiment was made from two flexible polyurethane foam slabs (to form the seat and back of the chair) and covered with fabric as shown in Figure 3. The foam was 28 kg/m³ cushion grade non-fire retardant treated and the fabric was 10 g/m² acrylic. The foam was typical of that used in domestic furniture in New Zealand. Each foam slab measured 500 mm x 400 mm x 100 mm in size, weighed approximately 0.56 kg and was arranged to form the seat as shown in

Figure 3. Plasterboard (10 mm) was used to form a backing board for the seat assembly to prevent the foam from dropping to the floor when burning. The chair was placed on a load cell to record the mass loss during the experiment with the base of the seat approximately 0.65 m above the floor. The seat was ignited with a solid petroleum fire-lighter (20 mm x 20 mm x 10 mm) positioned at the interface between the back and the seat.



Figure 3. Upholstered chair in centre fire position (extracted from Bittern [10])

The average heat of combustion of the foam was measured in a cone calorimeter to be 21.0 MJ/kg (tests 1–10) and 20.4 MJ/kg (tests 11–22). This was used with the measured mass loss rate for each experiment to determine the rate of heat release of the chair.

Two sprinkler heads spaced 4 m apart and generally complying with the New Zealand Standard NZS 4541:2003 [12] were installed beneath the ceiling for each experiment. There were four different models of sprinkler head used for the experiments. They were:

1. Residential Type A: pendent, nominal activation temperature 68°C (TYCO F680)
2. Residential Type B: pendent, nominal activation temperature 68°C (TYCO 2234)
3. Standard Response SS68: pendent, standard coverage, nominal activation temperature 68°C (TYCO 3251)
4. Standard Response SS93: pendent, standard coverage, nominal activation temperature 93°C (TYCO 3251).

The four sprinkler heads were supplied by the manufacturer TYCO and were selected based on sprinkler head availability. The selected sprinkler heads provided a variation in activation temperature and RTI.

The sprinkler heads were not charged with flowing water during the experiment, but the pipe sections connected to the head did contain water under pressure. This was achieved by holding the water back with a closing valve in the pipe network. Pressure gauges were also installed immediately upstream of each sprinkler head, but before the closing valve, to indicate sprinkler activation.

Technical data for each sprinkler head is shown in Table 2. The RTI was based on a manufacturer’s estimate. Tsui [13] measured the conduction factor for a residential head similar to those used in this study. He estimated a value for the conduction factor in the range 0.33–0.45 (m/s)^{1/2} with an estimated uncertainty of up to 20%. On this basis, a conduction factor of 0.4 (m/s)^{1/2} was selected for the base case for all the sprinklers in this study.

The glass bulbs were typically about 20 mm long, with the mid-point located approximately 15 mm below the ceiling. The heat-sensitive element therefore spanned a depth from 5–25 mm below the ceiling.

Table 2. Sprinkler head data (base case)

	Activation temperature	RTI	C-factor
Residential Type A (3 mm glass bulb)	68°C	36 m ^{1/2} s ^{1/2}	0.4 (m/s) ^{1/2}
Residential Type B (3 mm glass bulb)	68°C	36 m ^{1/2} s ^{1/2}	0.4 (m/s) ^{1/2}
Standard Response SS68 (5 mm glass bulb)	68°C	95 m ^{1/2} s ^{1/2}	0.4 (m/s) ^{1/2}
Standard Response SS93 (5 mm glass bulb)	93°C	95 m ^{1/2} s ^{1/2}	0.4 (m/s) ^{1/2}

Experiment results

Table 3 shows a summary of the 44 sprinkler head activation times recorded during the experiments [10]. The radial distance from the centre of the fire plume to each sprinkler head was 2 m for experiments 1–15. Regarding experiments 16–22 with the corner fire location, the radial distances between the fire and the sprinkler heads were 2.8 m and 6.3 m for heads 1 and 2 respectively.

	Expt	ID	Head 1	Time (sec)	ID	Head 2	Time (sec)	T_{ambient} (°C)
Fire in centre of room / door open	1	1ResA	Res A	210	1ResA	Res A	250	23.7
	2	2ResA	Res A	225	2ResA	Res A	211	25.5
	3	3ResB	Res B	192	3ResB	Res B	192	25.5
	4	4SS68	SS68	226	4SS68	SS68	226	25.7
	5	5SS68	SS68	266	5SS68	SS68	272	27.5
	6	6SS68	SS68	216	6SS68	SS68	211	27.7
	7	7ResB	Res A	182	7ResA	Res A	186	28.2
	8	8ResB	Res B	182	8ResB	Res B	187	27.9
	9	9ResB	Res B	233	9ResB	Res B	230	28.9
	10	10ResA	Res A	183	10ResB	Res B	184	29.4
Fire in centre of room / door shut	11	11SS68	SS68	199	11ResB	Res B	175	–
	12	12SS68	SS68	246	12ResB	Res B	228	24.0
	13	13SS68	SS68	204	13ResB	Res B	194	24.5
	14	14SS68	SS68	203	14ResB	Res B	187	24.2
	15	15SS68	SS68	270	15ResB	Res B	253	23.7
Fire in corner of room / door shut	16	16ResB	Res B	178	16ResA	Res A	244	20.6
	17	17ResB	Res B	181	17ResA	Res A	228	23.8
	18	18SS68	SS68	187	18ResA	Res A	221	25.0
	19	19SS68	SS68	189	19ResA	Res A	223	26.4
	20	20SS68	SS68	205	20ResA	Res A	None	25.3
	21	21SS93	SS93	216	21SS93	SS93	330	25.2
	22	22SS93	SS93	205	22SS93	SS93	263	25.2

Table 3. Activation result summary (from [10])

The recorded activation times indicate that the type of sprinkler head has a significant influence on the sprinkler activation time. The results of experiments 11–15 show that under the same fire and door (closed) condition, but with two different sprinkler heads mounted in the room, Residential Type B responded quicker than Standard Response SS68. This is as expected as Residential Type B is more sensitive than Standard Response SS68 due to a smaller RTI value, even though they both have the same activation temperature. The effect of the activation temperature is also apparent from comparing the results of experiments 18–22 for head 1. Both have the same nominal RTI value; however Standard Response SS68 responded quicker than Standard Response SS93.

The position of the fire relative to the sprinkler head is also an important parameter influencing the sprinkler activation time. With the fire placed mid-way between sprinklers (experiments 1–9) and the door open, the difference in activation times for two identical sprinkler heads in the same experiment ranged from 0–40 seconds, with an average variation of 9 seconds. For the corner fire, however, the activation time for the respective sprinkler heads varied considerably. Comparing sprinkler activation times for experiments 16–22, sprinkler head 1, which was closer to the fire source, responded at least 30 seconds earlier than sprinkler head 2.

It is difficult to conclude whether the door open/closed configuration had any effect on sprinkler activation times from the limited experimental data. The difference in sprinkler activation times for both door open and shut appeared insignificant.

SIMULATIONS

Scenarios

The scenarios investigated were:

1. Simulations using base case values for the sprinkler parameters in conjunction with the NIST/JET and Alpert's ceiling jet correlations respectively. The base case values are given in Table 4.
2. A sensitivity analysis investigating the effect of changing the RTI on the standard response sprinkler activation time for the NIST/JET ceiling jet option. RTI's of 85, 95 and 105 $\text{m}^{1/2}\text{s}^{1/2}$ were considered.
3. A sensitivity analysis investigating the effect of changing the C-factor on the sprinkler activation time for the NIST/JET ceiling jet option. C-factors of 0.2, 0.4 and 0.6 $(\text{m/s})^{1/2}$ were considered.
4. A sensitivity analysis investigating the effect of changing the sprinkler position below the ceiling for the NIST/JET ceiling jet option. Additional simulations were done with positions

below the ceiling of 5 mm and 25 mm (the extreme ends of the bulb) to assess the effect of this parameter on the sprinkler activation time.

Measurement showed the depth from the ceiling level to the mid-point of the sprinkler glass bulb was approximately 15 mm for both Residential Type A or B and Standard Response SS68 or SS93. Both sprinkler types have an approximate 20 mm glass bulb length with a 5 mm plate depth on top.

The simulations were run using the base case values describing the sprinkler characteristics as shown in Table 4 with both NIST/JET and Alpert’s ceiling jet options available within the BRANZFIRE fire model.

Sprinkler type	Parameters	Value	Note
Residential Type A or B (68°C activation temperature)	C-factor	0.4 (m/s) ^{1/2}	estimated by Tsui
	RTI	36 m ^{1/2} s ^{1/2}	based on manufacturer’s estimate
	depth below ceiling	20 mm	glass bulb estimated to project 5–25 mm below ceiling
Standard Response SS68 and SS93	C-factor	0.4 (m/s) ^{1/2}	estimated by Tsui
	RTI	95 m ^{1/2} s ^{1/2}	based on manufacturer’s estimate
	depth below ceiling	20 mm	glass bulb estimated to project 5–25 mm below ceiling

Table 4. Sprinkler base case values

Other model inputs

For each simulation the estimated HRR for each experiment, based on the measured mass loss rate, was used as input. Although the fire source and ignition scenario were identical there was variability in the HRR between experiments. Figure 4 shows the calculated HRR for each of the experiments 1–10. After 180 seconds, the mean rate of heat release was 78.1 kW with a standard deviation of 29.6 kW.

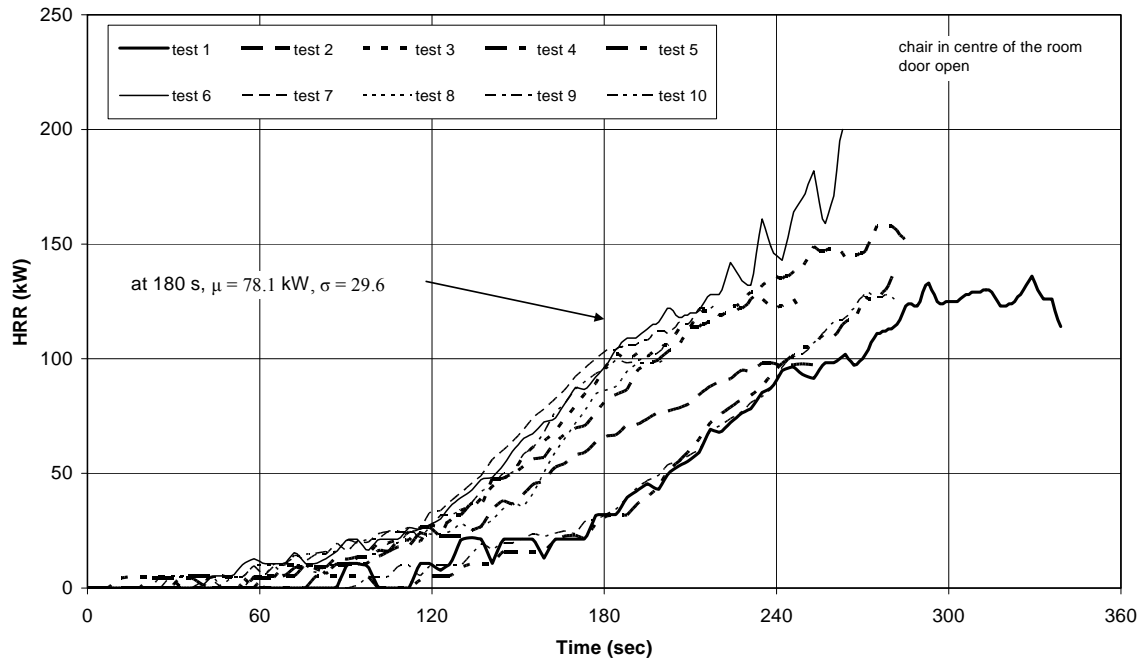


Figure 4. Rate of heat release for experiments 1–10

The fire was located in the room centre or corner as appropriate. The compartment dimensions and door opening size were as described earlier. For experiments 12–22, where the door to the room was closed, compartment/door leakage was not modelled. This was found to make a negligible difference to the results.

Since the primary fuel was flexible polyurethane foam, the radiant loss fraction assumed in the fire model was 0.46 based on the ratio of the radiative to chemical heat of combustion for GM23 foam from the literature [14]. A higher radiant loss fraction in the fire model reduces the convective energy in the ceiling jet and increases the predicted sprinkler response time. Other combustion parameter settings in the fire model were as for polyurethane foam. A summary of the fire model input data is given in Table 5.

Fire model	BRANZFIRE ver. 2005.2
Plume option	McCaffrey's correlation
Thermal properties – walls and ceiling 10 mm gypsum plasterboard	$\rho = 731 \text{ kg/m}^3$ $k = 0.17 \text{ W/mK}$ $\varepsilon = 0.88$
Thermal properties – floor 100 mm concrete	$\rho = 2300 \text{ kg/m}^3$ $k = 1.2 \text{ W/mK}$ $\varepsilon = 0.50$
Ambient conditions	RH = 65% ambient temperature as per the experiments
Fuel radiant loss fraction	0.46
Heat of combustion	21.0 MJ/kg (tests 1–10) 20.4 MJ/kg (tests 11–22)
Soot yield	0.227 g/g
Height of fire above floor	0.65 m

Table 5. Summary of fire model input data

Simulation results

Figure 5 shows a comparison of the measured and predicted sprinkler activation times for the base case with the JET ceiling jet option. Simulations were terminated at 600 seconds – when no activation was predicted during that time it appears as 600 seconds on the figure. For experiments (1–15), with the fire located centrally between the sprinkler heads, on average the prediction was 21% longer than the measured activation times. In the case of the corner fire experiments (16–22), agreement between the predictions and experiments was reasonable (37% longer) for the sprinkler head located nearest the fire (at 2.8 m), but agreement was poor (98% longer – for experiments 16–19) for the sprinkler head located furthest from the fire (at 6.3 m), suggesting that the drop-off in ceiling jet temperature with radial distance in the model was too great compared to the actual case.

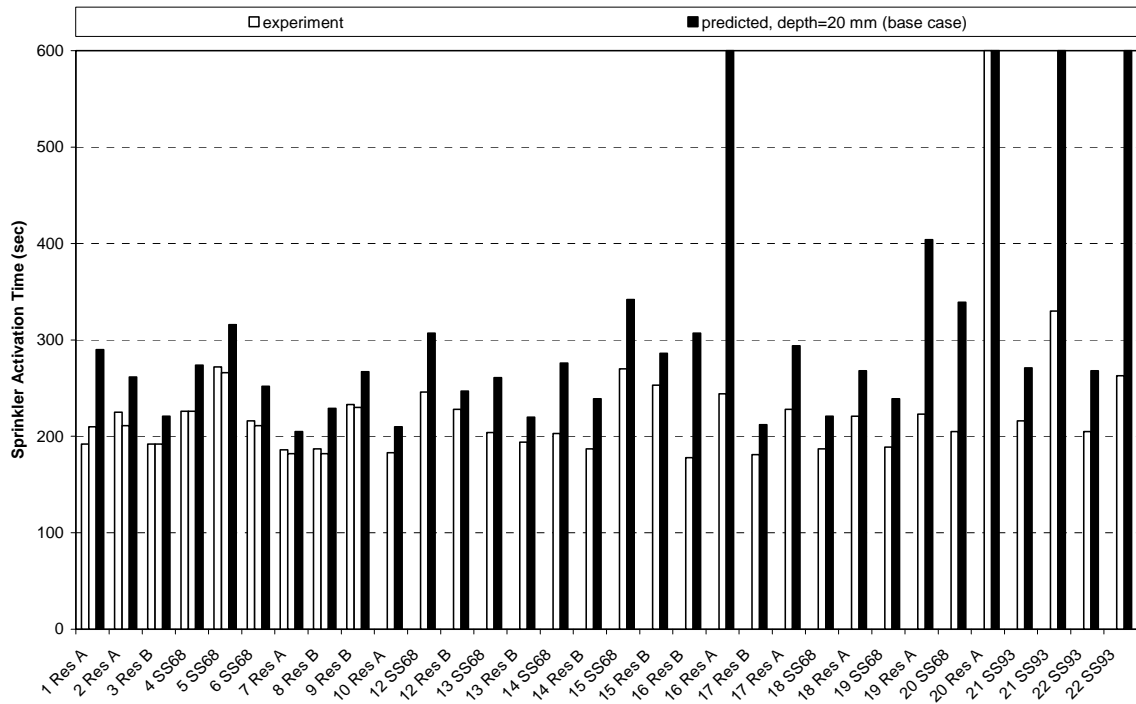


Figure 5. Comparison of measured and predicted activation time for base case – with BRANZFIRE/JET model

Figure 6 shows a comparison of the measured and predicted sprinkler activation times for the base case with the ALPERT ceiling jet option. In this case the predicted activation times were significantly longer than the measured times. This observation is not unexpected since the Alpert ceiling jet correlations were developed for fire flows beneath an unconfined ceiling and therefore they do not allow for the presence of a hot upper layer in the room. The experiments were conducted within an enclosure where an upper layer was allowed to develop. Heat transfer from the hot upper layer will increase the rate at which the temperature of the sprinkler bulb rises, and therefore will reduce the activation time of the sprinkler.

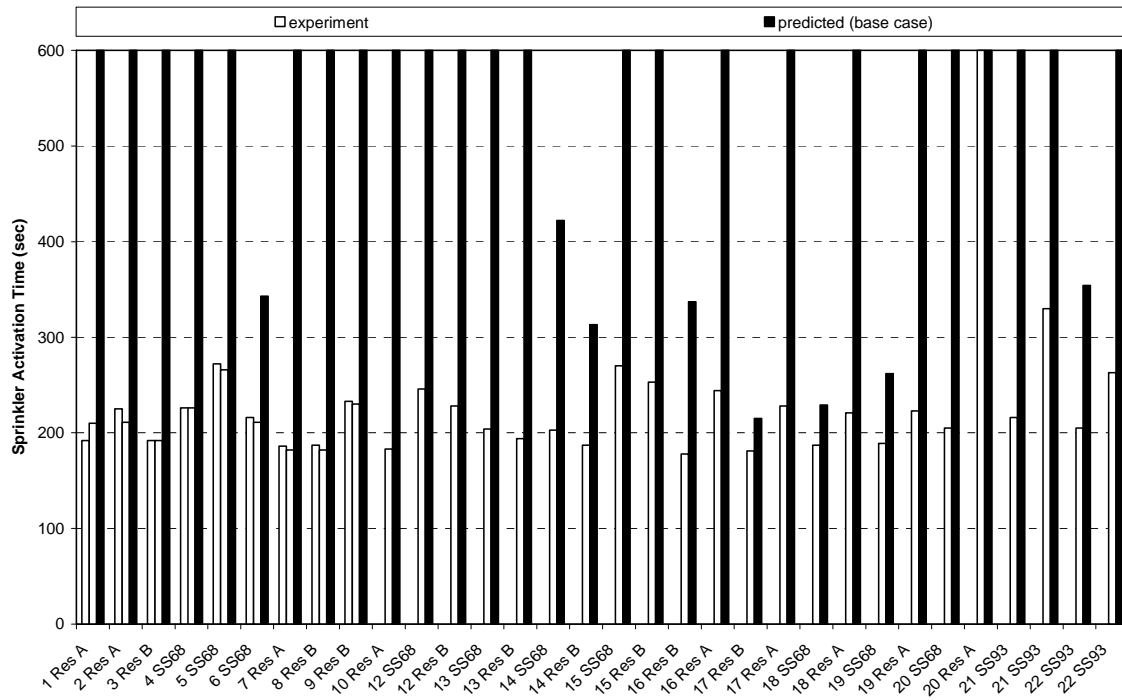


Figure 6. Comparison of measured and predicted activation time for base case – with BRANZFIRE/ALPERT model

Gas temperatures at the sprinkler location

Figure 7 compares the measured and predicted gas temperatures (in the ceiling jet) at the location of the sprinkler at the measured time of sprinkler activation. The predicted gas temperatures (based on the JET ceiling jet option) are generally higher than the measured gas temperatures, with a few exceptions. Better agreement is achieved for the centre fires compared with the corner fires. Given that the predicted sprinkler response times are longer than the measured times, this result suggests that the assumed thermal response characteristics for the sprinklers are conservative.

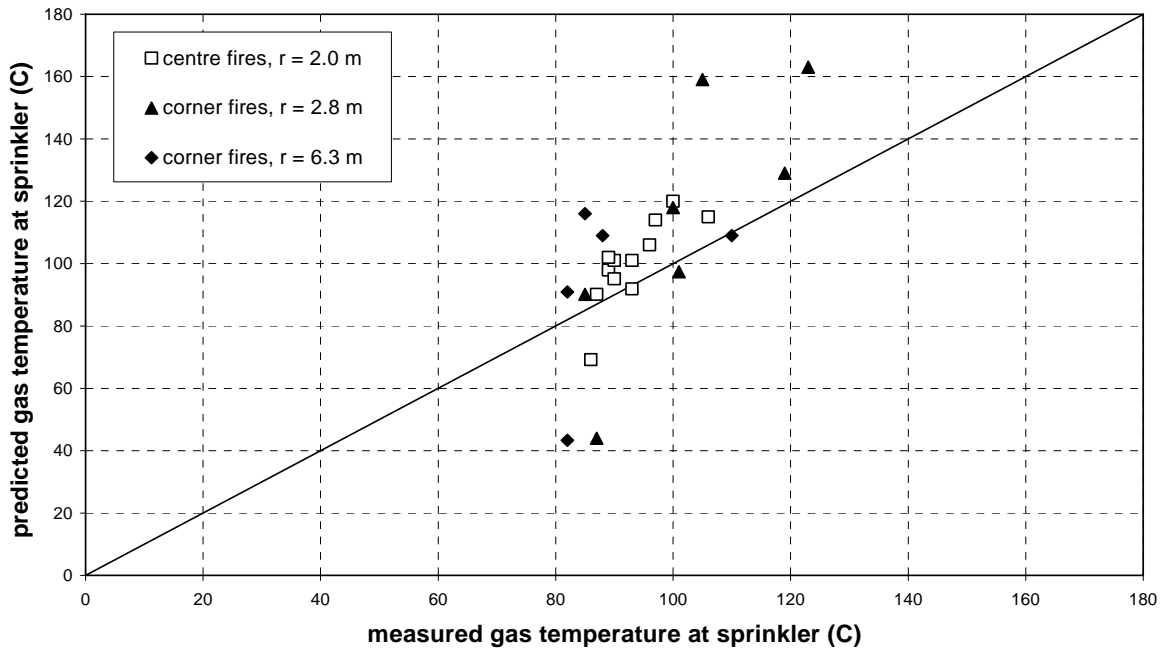


Figure 7. Comparison of the measured and predicted gas temperatures at the location of the sprinkler at the measured sprinkler activation time

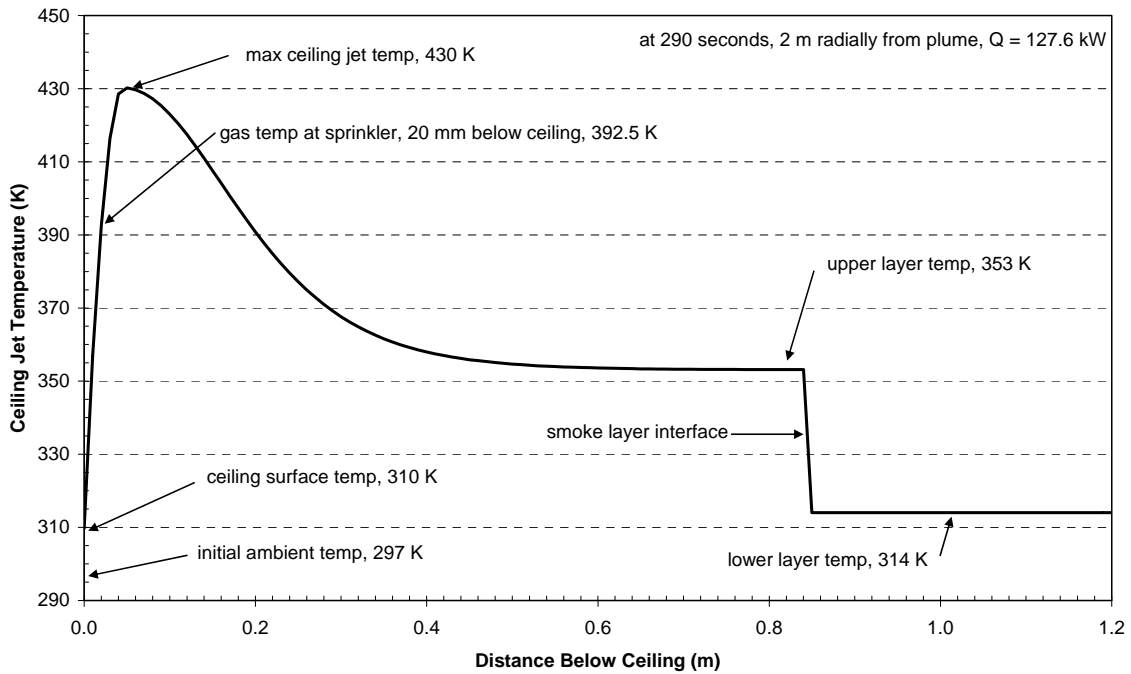


Figure 8. Simulated gas temperature profile for experiment 1 at time of predicted sprinkler activation

As observed in Figure 7, there is a steep temperature gradient modelled close to the ceiling representing a transition from the ceiling surface temperature to the maximum ceiling jet temperature. For a ceiling height of 2.4 m and radial distance from the plume of 2 m, the depth at which the ceiling jet temperature is at a maximum is 47 mm (using $d_{\max} = 0.023H[r/H]^{0.9}$). This increases to 132 mm for a radial distance of 6.3 m. Therefore, for these experiments, the sprinkler bulbs were positioned well above the expected depth at which the maximum ceiling jet temperature occurs.

To illustrate the simulated variation of the gas temperature with depth beneath the ceiling, Figure 8 shows the assumed gas temperature profile over the height of the room for experiment 1 at 290 seconds.

Sensitivity analysis – response time index (RTI)

Wind tunnel tests on the Standard Response SS68 sprinkler head by Tsui [13] obtained a mean RTI value of $97 \text{ m}^{1/2}\text{s}^{1/2}$, a minimum RTI value of $92 \text{ m}^{1/2}\text{s}^{1/2}$ and a maximum RTI value of $104 \text{ m}^{1/2}\text{s}^{1/2}$. Thus, additional simulations were conducted for the standard sprinkler heads SS68 and SS93 using an RTI of 85 and $105 \text{ m}^{1/2}\text{s}^{1/2}$ giving variations of $10 \text{ m}^{1/2}\text{s}^{1/2}$ from the base case. Figure 9 shows a comparison of the measured and predicted standard response sprinkler activation times for the BRANZFIRE/JET model with varying RTI. As expected, a lower RTI led to a shorter predicted response time and vice versa.

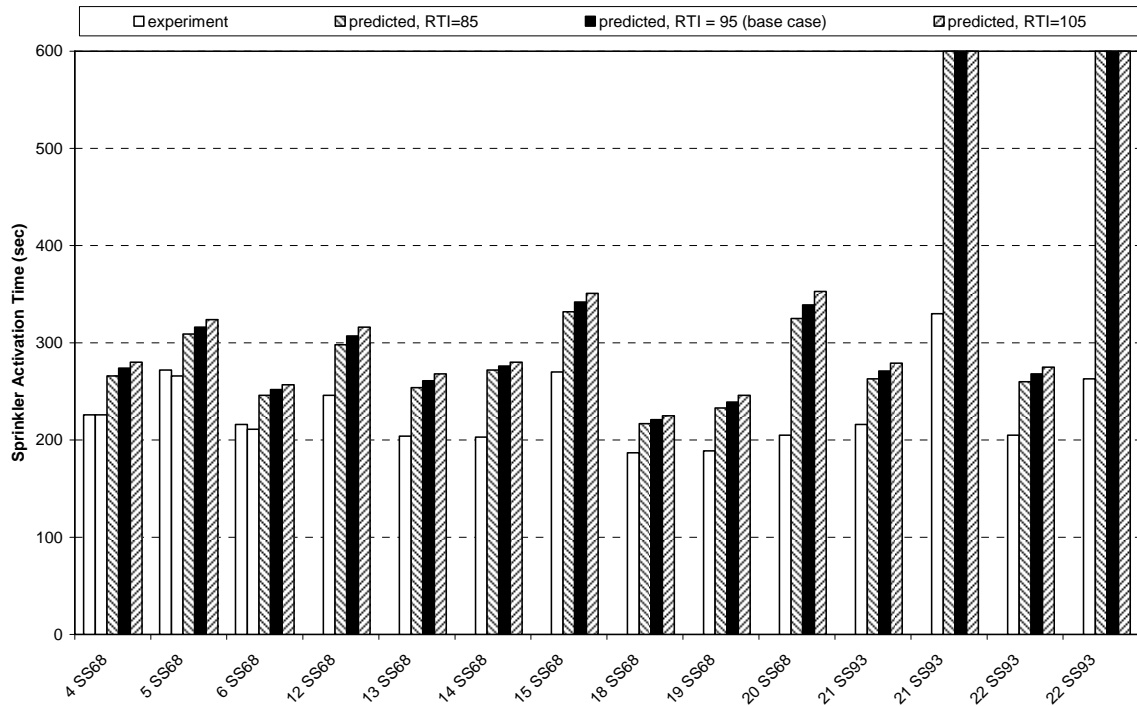


Figure 9. Effect of changing the RTI on the standard response sprinkler activation time

Sensitivity analysis – conduction factor

Additional simulations were done with a sprinkler conduction factor (C-factor) of 0.2 and 0.6 (m/s)^{1/2} representing variations of ±50 % from the base case. For experiments (1–15) with the fire located centrally between the sprinkler heads, a 50% reduction in C-factor led to an average 5.6 % reduction in the predicted activation time, while a 50% increase in the C-factor led to an average 7.9% increase in the predicted activation time. Figure 10 shows a comparison of the measured and predicted sprinkler activation times for the JET ceiling jet option with varying C-factor.

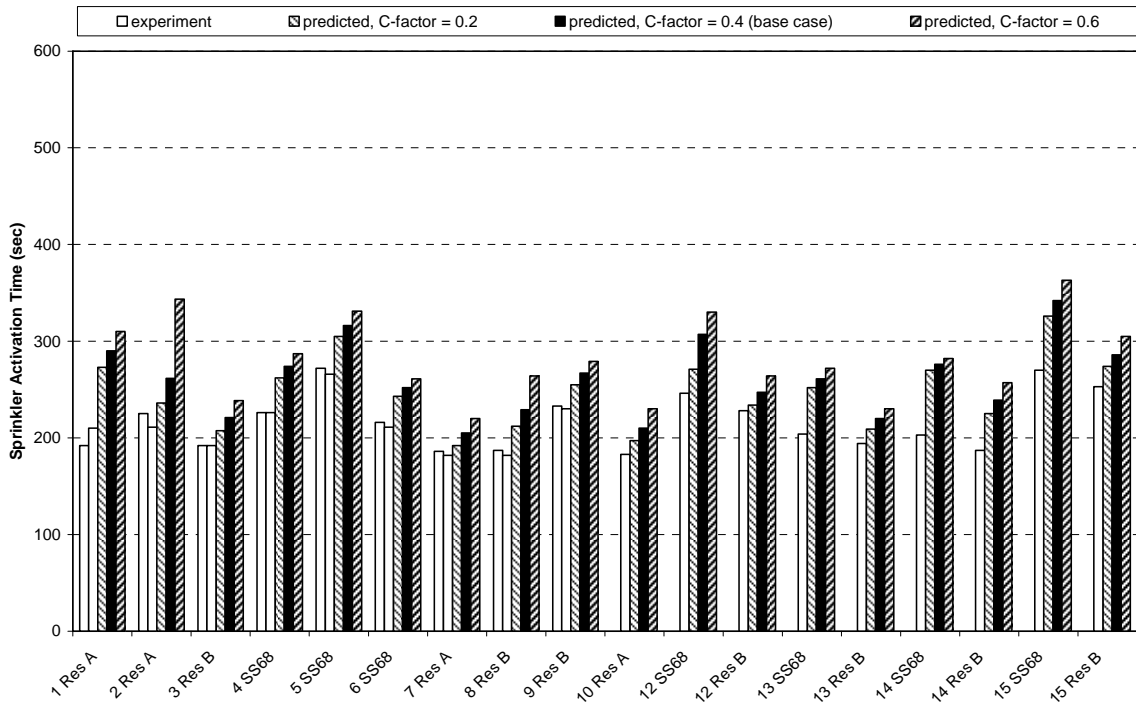


Figure 10. Effect of changing the conduction factor on the sprinkler activation time

Sensitivity analysis – sprinkler position beneath the ceiling

Figure 11 shows a comparison of the measured and predicted sprinkler activation times for the JET ceiling jet option with various positions of the sprinkler bulb beneath the ceiling. It can be seen that the lower extreme end of the sprinkler bulb (at 25 mm) provides the best agreement with the experimental results, with poorer agreement obtained as the sprinkler depth is moved closer to the ceiling. At 5 mm from the ceiling, the predicted activation times become significantly longer. These results complement the investigation of gas temperatures below the ceiling since the depth at which the ceiling jet temperature is at a maximum has already been calculated to be 47 mm for these experiments.

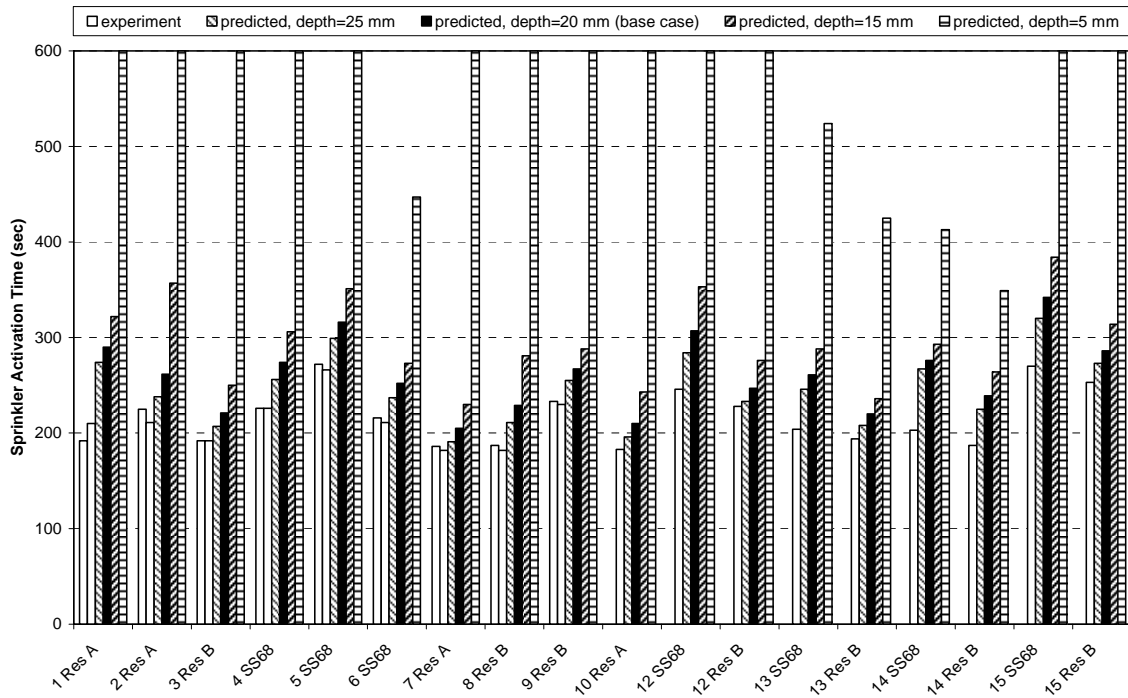


Figure 11. Effect of changing the sprinkler depth below ceiling on the sprinkler activation time

CONCLUSIONS

The response of sprinklers in small rooms is strongly influenced by the presence of a developing hot layer. If using the BRANZFIRE model for predicting sprinkler response times, the use of the JET ceiling jet option is recommended, particularly for small rooms, as better agreement with experimental results is expected.

The JET ceiling jet option (for the base case) gave sprinkler activation times that were, on average, 21% longer than the measured response times for fires located in the centre of the room. Furthermore, the mismatch of the predictions based on the JET ceiling jet model and the experimental results increases with distance from the plume. The use of the Alpert ceiling jet option indicated much longer response times in small rooms compared to actual response times. However, usually this would be considered conservative for design purposes.

The position of the sprinkler head beneath the ceiling is an important parameter and has a strong influence on the predicted ceiling jet temperature at the sprinkler position and therefore the response time of the sprinkler. It was found that simulations using the maximum depth below the ceiling of 25 mm gave the closest match with the experimental data. Values for the RTI and C-factor were found to be not so critical when comparing the simulations and experiments. The estimated RTI values

provided by the supplier and a typical C-factor of $0.4 \text{ (m/s)}^{1/2}$ gave reasonable results and would be appropriate for design purposes.

The ability to accurately model sprinkler activation not only relies on the depiction of their operational characteristics, but also depends on the accuracy of the ceiling jet conditions which in turn are a function of the source fire term. In the case of the modelling presented in this paper, sources of uncertainty are introduced in the fire growth input through the measurement of the mass loss rate and the determination of the heat of combustion. The assumptions necessary for the zone modelling approach introduce the potential for additional errors which affect any comparison between simulations and experimental results. Given these limitations, the results presented in this paper from using the JET ceiling jet option in BRANZFIRE can be considered to give a reasonable match with the experimental data.

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NOMENCLATURE

c_p = specific heat (kJ/kgK)

C = sprinkler conduction factor $(\text{m/s})^{1/2}$

d = location of sprinkler head beneath ceiling (m)

H = height of the ceiling above the base of the fire (m)

\dot{h}_l = rate of enthalpy change in the lower layer (kW)

\dot{h}_u = rate of enthalpy change in the upper layer (kW)

k = thermal conductivity (W/mk)

\dot{m}_l = rate of mass in the lower layer (kg/s)

\dot{m}_u = rate of mass in the upper layer (kg/s)

P = compartment pressure at floor level (Pa)

\dot{Q} = heat release (kW)

r = radial distance from the centre of the plume (m)

RTI = response time index ($m^{1/2}s^{1/2}$)

t = time (s)

T_e = temperature of sprinkler link (K)

T_{cj} = the temperature of the ceiling jet (K)

T_{int} = the initial temperature of the compartment (K)

T_l = lower layer temperature (K)

T_u = upper layer temperature (K)

U_{cj} = velocity of the ceiling jet (m/s)

V_R = compartment volume (m^3)

V_u = upper layer volume (m^3)

γ = ratio of specific heats

ε = emissivity

ρ = material density (kg/m^3)

ρ_u = upper layer gas density (kg/m^3)

ρ_l = lower layer gas density (kg/m^3)

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